

| 112 MadhuaMaatar madhua maatar | | | | Library | | |
|---|--|---|---------------|-------------------------|--|--|
| 1.1.3 Moususwaster, mousus master | | | FB | eLLabUtyLib_C030 | | |
| This function performs the management of Modbus RTU, Ascii, TCP master protocol (Selectable by Type). You can define the File I/O terminal on which to communicate. Setting the Enable , on the terminal I/O is sent a frame to execute the modbus function defined in the FCode . Once the Enable Done - command execution is finished the Done output is activated. If the command execution is Enable Done Ok - successful the Ok output will be set for a program loop. By disabling Enable the Done and Fault - File Fault - Type Errors - Type Type Errors - Type | | | | | | |
| If <i>FCode</i> is a read function, the value of variables starting from <i>Address</i> for the number of variables - Node defined by <i>Points</i> , is read from the slave system and transferred into the variables addressed by - FCode <i>Buffer</i> . The <i>SpyOn</i> input allows to spy the FB working Address | | | | | | |
| If <i>FCode</i> is a write defined by <i>Points</i> , | If <i>FCode</i> is a write function, the value of variables addressed by <i>Buffer</i> for the number of variables buffer address address. | | | | | |
| On error executing command or command execution time bigger than the defined <i>Timeout</i> , the <i>Fault</i> output will be activated for a program loop and the <i>Errors</i> counter increased. | | | | | | |
| Enable (BOOL) | Command re-enable | that enables Modbus command execution. To re-exe this input. | ecute the con | nmand, disable and then | | |
| SpyOn (BOOL) | Active allo | ws to spy the FB working. | | | | |
| File (FILEP) | Stream returned from <u>Sysfopen</u> function. | | | | | |
| Type (USINT) | Modbus type selector. 0:RTU, 1:Ascii, 2:TCP | | | | | |
| Node (USINT) | Modbus node number on which to execute command (Range from 0 to 255). | | | | | |
| FCode (USINT) | Modbus code function to execute (Range from 0 to 255). | | | | | |
| | Code | Description | | | | |

| | Code | Description | | | |
|----------------|---|--|--|--|--|
| | 16#01 | Read coil status (Max 255 coils) | | | |
| | 16#02 | Read input status (Max 255 inputs) | | | |
| | 16#03 Read holding registers (Max 32 registers) | | | | |
| | 16#04 Read input registers (Max 32 registers) | | | | |
| | 16#06 | Preset single register | | | |
| | 16#0F | Force multiple coils (Max 255 coils) | | | |
| | 16#10 | Preset multiple registers (Max 32 registers) | | | |
| Address (UINT) | Address allocation of variables on slave system. According to the Modbus specifications, the address sent in the frame is (<i>Address-1</i>) (Range from 16#0001 to 16#FFFF). | | | | |
| Points (USINT) | Number of consecutive variables on which the command operates. | | | | |

Buffer (@USINT) Address of buffer of read or written data.



IFTime (UDINT)

UDINT) Time between frame (μ S).

If you use the serial port, this time must be related to baud rate.

| Baud rate | Time | Baud rate | Time |
|-----------|--------|-----------|------|
| 300 | 112000 | 19200 | 1720 |
| 600 | 56000 | 38400 | 860 |
| 1200 | 28000 | 57600 | 573 |
| 2400 | 14000 | 76800 | 429 |
| 4800 | 7000 | 115200 | 286 |
| 9600 | 3430 | | |

On ethernet connection set the minimum time value.

Timeout (UINT) Maximum command execution time expressed in mS. If the command does not end in the defined time, the command is aborted and the *Fault* output is activated.

Delay (UINT) Pause time after the execution of the command modbus expressed in mS.

- **Done** (BOOL) Active at the end of command execution.
- **Ok** (BOOL) Active for a program loop if command correctly executed.

Fault (BOOL) Active for a program loop if execution error.

SpyTrg (UDINT) Trigger for the SpyDataFile FB.

SpyPtr (@USINT) Pointer to data to be spy.

Errors (UDINT) Error counter. Increased at every error. If it reach the maximum value, it restarts from 0.

Spy trigger

If **SpyOn** is active the <u>SysSpyData</u> function is executed this allows to spy the FB operations. There are various levels of triggers.

TFlags Description

16#00000001 Tx: Modbus command frame sent.

16#00000002 **Rx:** Modbus answer frame received.

Error codes

If an error occurs, the *Fault* output is activated and <u>SysGetLastError</u> can detect the error code.

10007010 *File* value not defined.

10007050 Execution timeout.

- 10007060 Execution error.
- 10037080 *Type* definition error.
- 10007100 Function code defined in *Function* is not managed.
- 10007120 Wrong Points value.
- 10007200~2 Error transmitting the command frame.

10007500~7 Error receiving the answer frame (Wrong character, wrong length, won CRC).



Examples

Here an example of reading from a slave SlimLine. Cyclically is performed a read of 16 coils starting from address 16#01 of Modbus node 1. The value of the coils is transferred to the *RxCoils* array. After the reading will be activated the *Do01M00* logic output for a program loop.

Defining variables

| | Name | Туре | Address | Array | Init value | Attribute | Description |
|---|---------|--------------|---------|-------|------------|-----------|-----------------------------|
| 1 | RxCoils | BOOL | Auto | [015] | 16(0) | | Rx coils data buffer |
| 2 | Errors | UDINT | Auto | No | 0 | | Modbus communication errors |
| 3 | Fp | FILEP | Auto | No | 0 | | File pointer |
| 4 | MdbSn | ModbusMaster | Auto | No | 0 | | Modbus master FB |

LD example (PTP114A620, LD_ModbusMaster)

